

# Overview

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## Earlier lecture

- Statistical sampling and Monte Carlo integration

## Last lecture

- Signal processing view of sampling

## Today

- Variance reduction
- Importance sampling
- Stratified sampling
- Multidimensional sampling patterns
- Discrepancy and Quasi-Monte Carlo

## Latter

- Path tracing for interreflection
- Density estimation

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# Cameras

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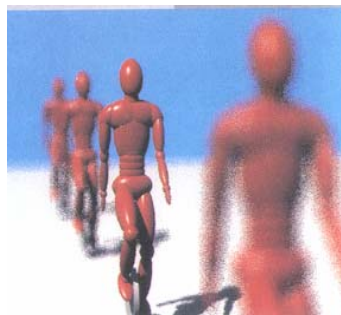
$$R = \int_T \int_\Omega \int_A L(x, \omega, t) P(x) S(t) \cos \theta dA d\omega dt$$

**Motion Blur**



Source: Cook, Porter, Carpenter, 1984

**Depth of Field**



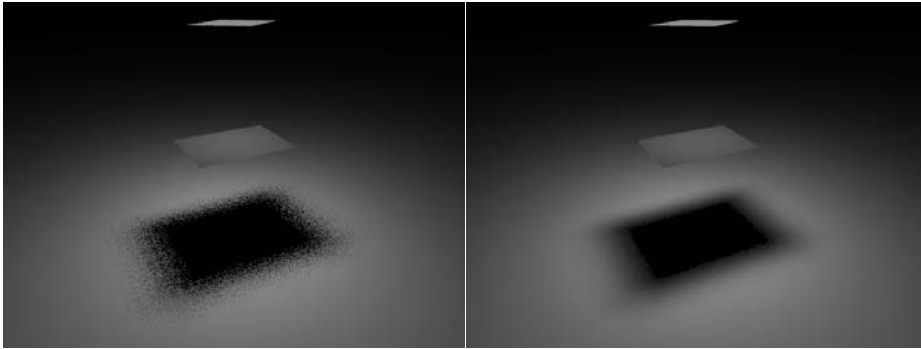
Source: Mitchell, 1991

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# Variance

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**1 shadow ray per eye ray**

**16 shadow rays per eye ray**

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# Variance

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## Definition

$$\begin{aligned}V[Y] &\equiv E[(Y - E[Y])^2] \\ &= E[Y^2] - E[Y]^2\end{aligned}$$

**Variance decreases with sample size**

$$V\left[\frac{1}{N} \sum_{i=1}^N Y_i\right] = \frac{1}{N^2} \sum_{i=1}^N V[Y_i] = \frac{1}{N^2} N V[Y] = \frac{1}{N} V[Y]$$

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## Variance Reduction

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Efficiency measure

$$\text{Efficiency} \propto \frac{1}{\text{Variance} \bullet \text{Cost}}$$

**If one technique has twice the variance as another technique, then it takes twice as many samples to achieve the same variance**

**If one technique has twice the cost of another technique with the same variance, then it takes twice as much time to achieve the same variance**

Techniques to increase efficiency

- Importance sampling
- Stratified sampling

## Biasing

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**Previously used a uniform probability distribution**

**Can use another probability distribution**

$$X_i \sim p(x)$$

**But must change the estimator**

$$Y_i = \frac{f(X_i)}{p(X_i)}$$

## Unbiased Estimate

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**Probability**  $X_i \sim p(x)$

**Estimator**  $Y_i = \frac{f(X_i)}{p(X_i)}$

$$\begin{aligned} E[Y_i] &= E\left[\frac{f(X_i)}{p(X_i)}\right] \\ &= \int \left[\frac{f(X_i)}{p(X_i)}\right] p(x) dx \\ &= \int f(x) dx \\ &= I \end{aligned}$$

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## Importance Sampling

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**Sample according to  $f$**

$$\tilde{p}(x) = \frac{f(x)}{E[f]}$$

$$\begin{aligned} \int \tilde{p}(x) dx &= \int \frac{f(x)}{E[f]} dx \\ &= \frac{1}{E[f]} \int f(x) dx \\ &= 1 \end{aligned}$$

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# Importance Sampling

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## Variance

$$V[f] = E[f^2] - E^2[f]$$

## Sample according to $f$

$$E[\tilde{f}^2] = \int \left[ \frac{f(x)}{\tilde{p}(x)} \right]^2 \tilde{p}(x) dx$$

$$\tilde{p}(x) = \frac{f(x)}{E[f]}$$

$$= \int \left[ \frac{f(x)}{f(x)/E[f]} \right]^2 \frac{f(x)}{E[f]} dx$$

$$\tilde{f}(x) = \frac{f(x)}{\tilde{p}(x)}$$

$$= E[f] \int f(x) dx$$

## Zero variance!

$$= E^2[f]$$

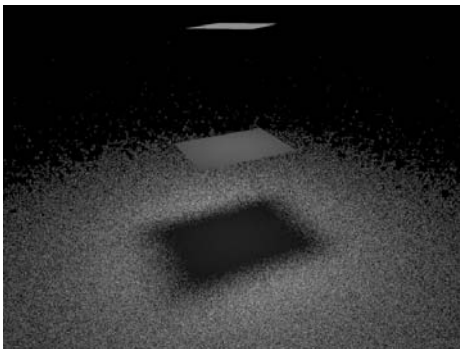
$$V[\tilde{f}^2] = 0$$

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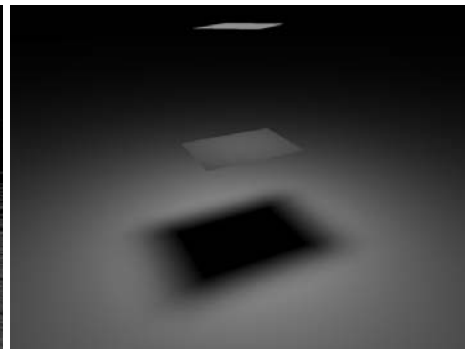
# Examples

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**Projected solid angle**

**4 eye rays per pixel  
100 shadow rays**



**Area**

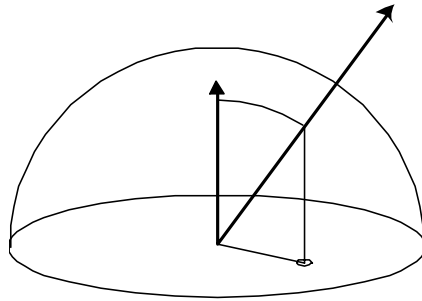
**4 eye rays per pixel  
100 shadow rays**

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# Irradiance

Generate cosine weighted distribution



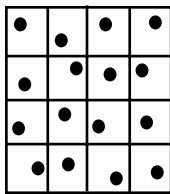
$$p(\omega) d\omega = \cos \theta d\omega$$

$$E = \int_{H^2} L_i(\omega_i) \cos \theta_i d\omega_i$$

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# Stratified Sampling



*Stratified sampling is like jittered sampling*

Allocate samples per region

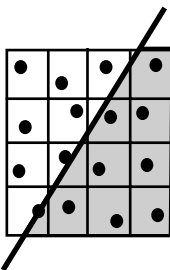
$$F_N = \frac{1}{N} \sum_{i=1}^N F_i$$

New variance

$$V[F_N] = \frac{1}{N^2} \sum_{i=1}^N V[F_i]$$

Thus, if the variance in regions is less than the overall variance, there will be a reduction in resulting variance

For example: An edge through a pixel



$$V[F_N] = \frac{1}{N^2} \sum_{i=1}^{\sqrt{N}} V[F_j] = \frac{V[F_E]}{N^{1.5}}$$

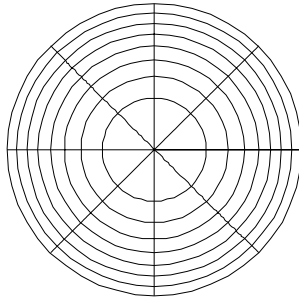
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# Sampling a Circle

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## Equi-Areal



$$\theta = 2\pi U_1$$

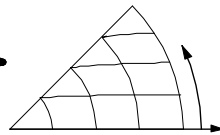
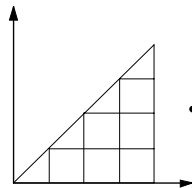
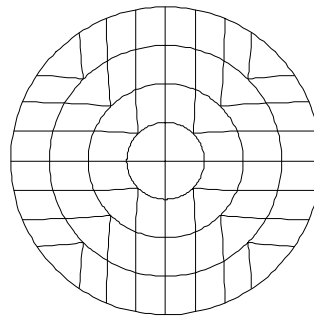
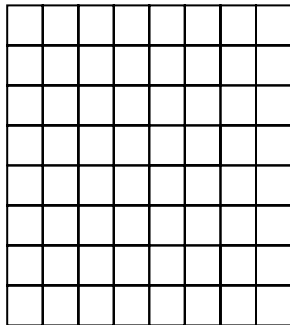
$$r = \sqrt{U_2}$$

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# Shirley's Mapping

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$$r = U_1$$

$$\theta = \frac{\pi U_2}{4 U_1}$$

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# High-dimensional Sampling

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## Numerical quadrature

For a given error ...

$$E \sim \frac{1}{n} = \frac{1}{N^{1/d}}$$

## Random sampling

For a given variance ...

$$E \sim V^{1/2} \sim \frac{1}{N^{1/2}}$$

*Monte Carlo requires fewer samples for the same error in high dimensional spaces*

# Block Design

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## Latin Square

|          |          |          |          |
|----------|----------|----------|----------|
| <i>a</i> | <i>d</i> | <i>c</i> | <i>b</i> |
| <i>b</i> | <i>a</i> | <i>d</i> | <i>c</i> |
| <i>c</i> | <i>b</i> | <i>a</i> | <i>d</i> |
| <i>d</i> | <i>c</i> | <i>b</i> | <i>a</i> |

Alphabet of size  $n$

Each symbol appears exactly once in each row and column

Rows and columns are stratified



# Block Design

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## N-Rook Pattern

|     |     |     |     |
|-----|-----|-----|-----|
| $a$ |     |     |     |
|     |     | $a$ |     |
|     | $a$ |     |     |
|     |     |     | $a$ |

**Incomplete block design**

**Replaced  $n^2$  samples with  $n$  samples**

**Permutations:**  $(\pi_1(i), \pi_2(i), \dots, \pi_d(i))$

**Generalizations: N-queens, 2D projection**

$$(\pi_x = \{1, 2, 3, 4\}, \pi_y = \{4, 2, 3, 1\})$$

# Space-time Patterns

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|    |    |    |    |
|----|----|----|----|
| 6  | 10 | 2  | 13 |
| 3  | 14 | 12 | 8  |
| 15 | 0  | 7  | 11 |
| 5  | 9  | 4  | 1  |

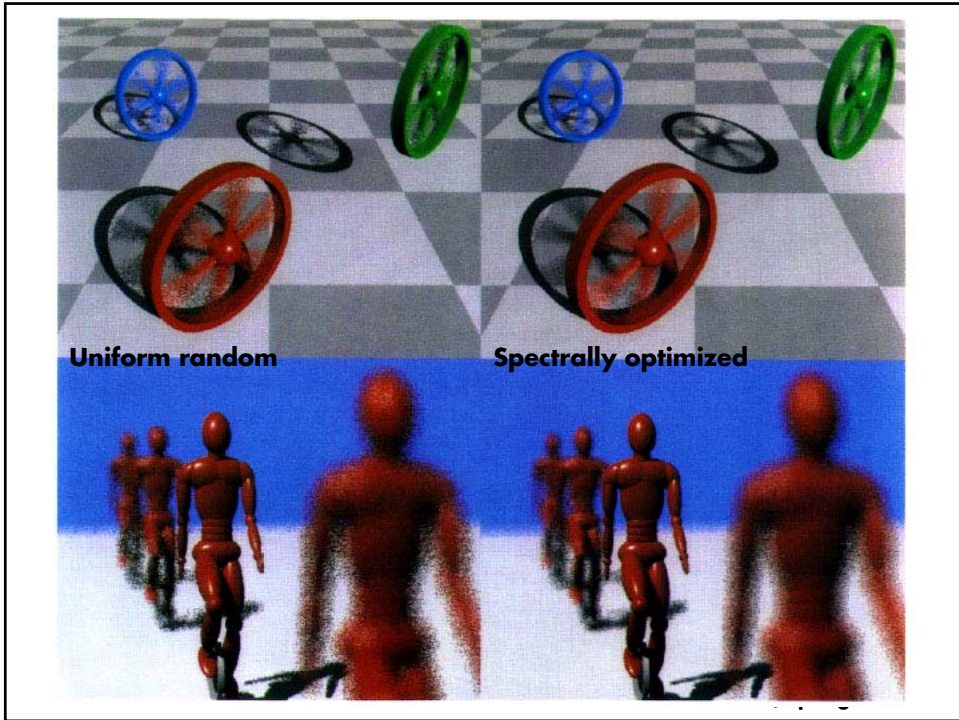
**Cook Pattern**

|    |    |    |    |
|----|----|----|----|
| 15 | 8  | 5  | 2  |
| 4  | 3  | 14 | 9  |
| 10 | 13 | 0  | 7  |
| 1  | 6  | 11 | 12 |

**Pan-diagonal Magic Square**

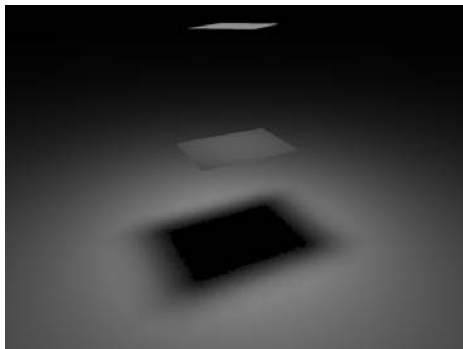
**Distribute samples in time**

- **Complete in space**
- **Samples in space should have blue-noise spectrum**
- **Incomplete in time**
- **Decorrelate space and time**
- **Nearby samples in space should differ greatly in time**



## Path Tracing

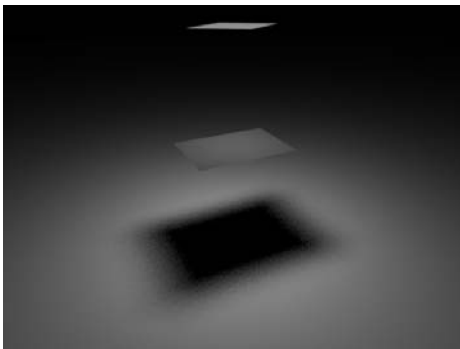
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**4 eye rays per pixel**  
**16 shadow rays per eye ray**

**Complete**

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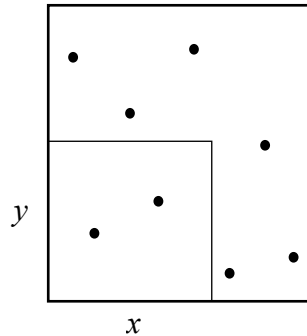


**64 eye rays per pixel**  
**1 shadow ray per eye ray**

**Incomplete**

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## Discrepancy



$$\Delta(x, y) = \frac{n(x, y)}{N} - xy$$

$$A = xy$$

$n(x, y)$  number of samples in  $A$

$$D_N = \max_{x, y} |\Delta(x, y)|$$

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## Theorem on Total Variation

**Theorem:** 
$$\left| \frac{1}{N} \sum_{i=1}^N f(X_i) - \int f(x) dx \right| \leq V(f) D_N$$

**Proof: Integrate by parts**

$$\begin{aligned} & \int f(x) \left[ \frac{\delta(x - x_i)}{N} - 1 \right] dx & \frac{\partial \Delta(x)}{\partial x} &= \frac{\delta(x - x_i)}{N} - 1 \\ &= \int f(x) \frac{\partial \Delta(x)}{\partial x} dx \\ &= f \Delta \Big|_0^1 - \int \frac{\partial f(x)}{\partial x} \Delta(x) dx = - \int \frac{\partial f(x)}{\partial x} \Delta(x) dx \\ &\leq D_N \int \left| \frac{\partial f(x)}{\partial x} \right| dx = V(f) D_N \end{aligned}$$

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# Quasi-Monte Carlo Patterns

## Radical inverse (digit reverse)

of integer  $i$  in integer base  $b$

$$\phi_2(i)$$

$$i = d_i \cdots d_2 d_1 d_0$$

$$\phi_b(i) \equiv 0.d_0 d_1 d_2 \cdots d_i$$

|          |            |             |            |
|----------|------------|-------------|------------|
| <b>1</b> | <b>1</b>   | <b>.1</b>   | <b>1/2</b> |
| <b>2</b> | <b>10</b>  | <b>.01</b>  | <b>1/4</b> |
| <b>3</b> | <b>11</b>  | <b>.11</b>  | <b>3/4</b> |
| <b>4</b> | <b>100</b> | <b>.001</b> | <b>3/8</b> |
| <b>5</b> | <b>101</b> | <b>.101</b> | <b>5/8</b> |

## Hammersley points

$$(i/N, \phi_2(i), \phi_3(i), \phi_5(i), \cdots)$$

$$D_N = O\left(\frac{\log^{d-1} N}{N}\right)$$

## Halton points (sequential)

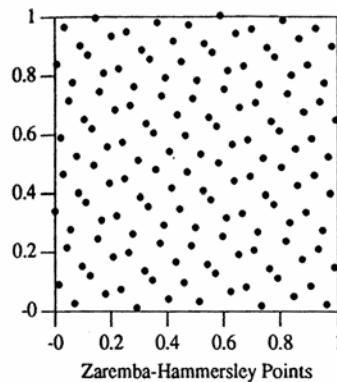
$$(\phi_2(i), \phi_3(i), \phi_5(i), \cdots)$$

$$D_N = O\left(\frac{\log^d N}{N}\right)$$

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# Hammersly Points



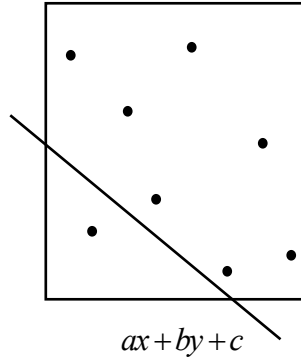
$$(i/N, \phi_2(i), \phi_3(i), \phi_5(i), \cdots)$$

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## Edge Discrepancy

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**Note: SGI IR Multisampling extension:  
8x8 subpixel grid; 1,2,4,8 samples**

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## Low-Discrepancy Patterns

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| Process      | 16 points | 256 points | 1600 points |
|--------------|-----------|------------|-------------|
| Zaremba      | 0.0504    | 0.00478    | 0.00111     |
| Jittered     | 0.0538    | 0.00595    | 0.00146     |
| Poisson-Disk | 0.0613    | 0.00767    | 0.00241     |
| N-Rooks      | 0.0637    | 0.0123     | 0.00488     |
| Random       | 0.0924    | 0.0224     | 0.00866     |

**Discrepancy of random edges, From Mitchell (1992)**

Random sampling converges as  $N^{-1/2}$

Zaremba converges faster and has lower discrepancy

Zaremba has a relatively poor blue noise spectra

Jittered and Poisson-Disk recommended

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# Views of Integration

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## 1. Signal processing

- Sampling and reconstruction, aliasing and antialiasing
- Blue noise good

## 2. Statistical sampling (Monte Carlo)

- Sampling like polling
- Variance
- High dimensional sampling:  $1/N^{1/2}$

## 3. Quasi Monte Carlo

- Discrepancy
- Asymptotic efficiency in high dimensions

## 4. Numerical

- Quadrature/Integration rules
- Smooth functions