

# Ray Tracing

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## Today

- Basic algorithms
- Ray-surface intersection for single surface

## Next lecture

- Acceleration techniques for ray tracing large numbers of geometric primitives

# Classic Ray Tracing

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**Greeks: Do light rays proceed from the eye to the light, or from the light to the eye?**

**Gauss: Rays through lenses**

**Three ideas about light**

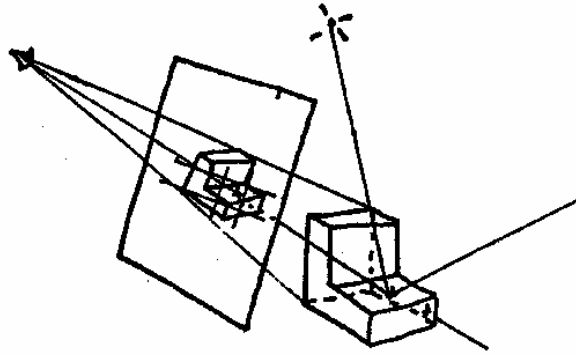
1. Light rays travel in straight lines
2. Light rays do not interfere with each other if they cross
3. Light rays travel from the light sources to the eye (but the physics is invariant under path reversal - reciprocity).

## Ray Tracing in Computer Graphics

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Appel 1968 - Ray casting

1. Generate an image by sending one ray per pixel
2. Check for shadows by sending a ray to the light

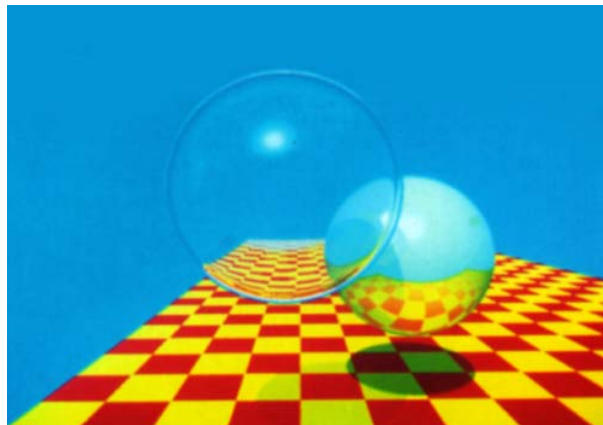


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## Ray Tracing in Computer Graphics

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Whitted 1979

Recursive ray tracing (reflection and refraction)

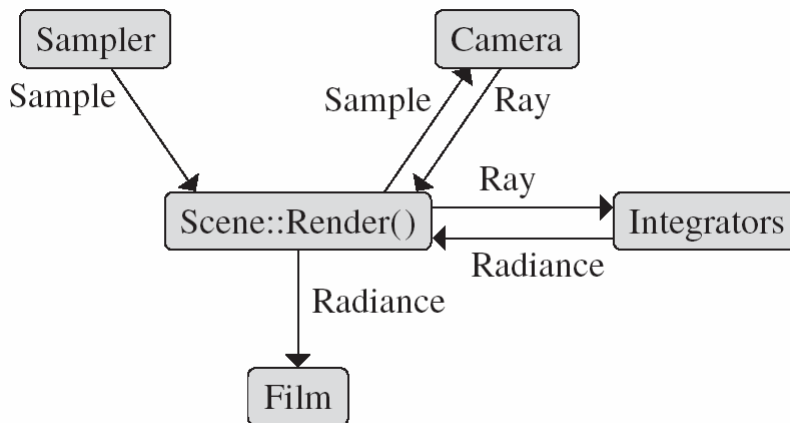
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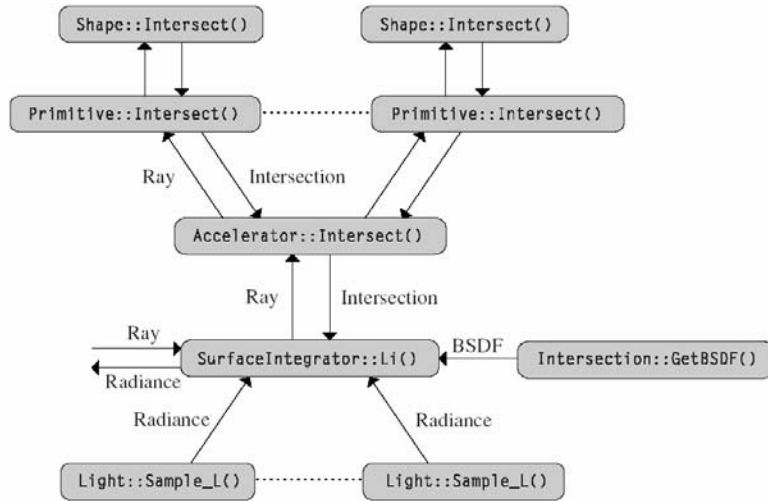
# Ray Tracing Demo

## PBRT Architecture

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# PBRT Architecture



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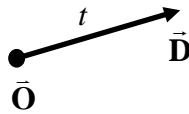
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## Ray-Surface Intersection

# Ray-Plane Intersection

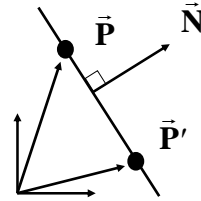
**Ray:**  $\vec{P} = \vec{O} + t\vec{D}$

$0 \leq t < \infty$



**Plane:**  $(\vec{P} - \vec{P}') \cdot \vec{N} = 0$

$ax + by + cz + d = 0$



**Solve for intersection**

**Substitute ray equation into plane equation**

$$(\vec{P} - \vec{P}') \cdot \vec{N} = (\vec{O} + t\vec{D} - \vec{P}') \cdot \vec{N} = 0$$

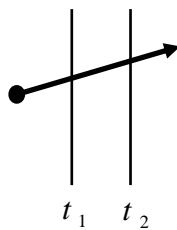
$$t = -\frac{(\vec{O} - \vec{P}') \cdot \vec{N}}{\vec{D} \cdot \vec{N}}$$

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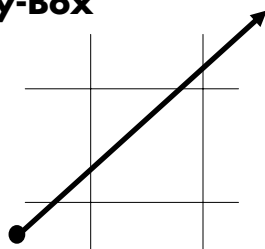
# Ray-Polyhedra

**Ray-Slab**

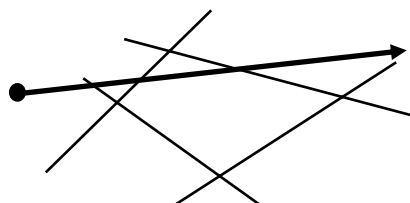


**Note: Procedural geometry**

**Ray-Box**



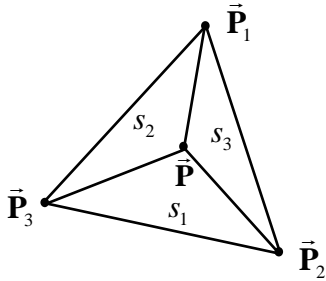
**Ray-Convex Polyhedra**



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# Ray-Triangle Intersection 1



## Barycentric coordinates

$$\vec{P} = s_1\vec{P}_1 + s_2\vec{P}_2 + s_3\vec{P}_3$$

## Inside triangle criteria

$$0 \leq s_1 \leq 1$$

$$0 \leq s_2 \leq 1$$

$$0 \leq s_3 \leq 1$$

$$s_1 + s_2 + s_3 = 1$$

$$s_1 = \text{area}(\Delta\vec{P}\vec{P}_2\vec{P}_3)$$

$$s_2 = \text{area}(\Delta\vec{P}\vec{P}_3\vec{P}_1)$$

$$s_3 = \text{area}(\Delta\vec{P}\vec{P}_1\vec{P}_2)$$

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# Ray-Triangle Intersection 2

$$\vec{P} = s_1\vec{P}_1 + s_2\vec{P}_2 + s_3\vec{P}_3$$

$$[\vec{P}_1 \quad \vec{P}_2 \quad \vec{P}_3] \begin{bmatrix} s_1 \\ s_2 \\ s_3 \end{bmatrix} = [\vec{P}]$$

$$\begin{bmatrix} s_1 \\ s_2 \\ s_3 \end{bmatrix} = \begin{bmatrix} \vec{P}_2 \times \vec{P}_3 \\ \vec{P}_3 \times \vec{P}_1 \\ \vec{P}_1 \times \vec{P}_2 \end{bmatrix} [\vec{P}]$$

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## Ray-Triangle Intersection 3

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$$\begin{bmatrix} s_1 \\ s_2 \\ s_3 \end{bmatrix} = \begin{bmatrix} \mathbf{P}_2 \times \mathbf{P}_3 \\ \mathbf{P}_3 \times \mathbf{P}_1 \\ \mathbf{P}_1 \times \mathbf{P}_2 \end{bmatrix} [\mathbf{P}]$$

$$s_1 = \frac{\begin{vmatrix} \mathbf{P} & \mathbf{P}_2 & \mathbf{P}_3 \\ \mathbf{P}_1 & \mathbf{P}_2 & \mathbf{P}_3 \end{vmatrix}}{\Delta} = \mathbf{P} \cdot \frac{\mathbf{P}_2 \times \mathbf{P}_3}{\Delta}$$

$$s_2 = \frac{\begin{vmatrix} \mathbf{P}_1 & \mathbf{P} & \mathbf{P}_3 \\ \mathbf{P}_1 & \mathbf{P}_2 & \mathbf{P}_3 \end{vmatrix}}{\Delta} = \mathbf{P} \cdot \frac{\mathbf{P}_3 \times \mathbf{P}_1}{\Delta}$$

$$s_3 = \frac{\begin{vmatrix} \mathbf{P}_1 & \mathbf{P}_2 & \mathbf{P} \\ \mathbf{P}_1 & \mathbf{P}_2 & \mathbf{P}_3 \end{vmatrix}}{\Delta} = \mathbf{P} \cdot \frac{\mathbf{P}_1 \times \mathbf{P}_2}{\Delta}$$

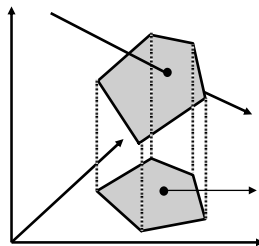
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## Ray-Polygon Intersection

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1. Find intersection with plane of support
2. Test whether point is inside 3D polygon
  - a. Project onto xy plane
  - b. Test whether point is inside 2D polygon



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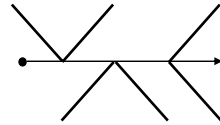
## Point in Polygon

```

inside(vert v[], int n, float x, float y)
{
    int cross=0; float x0, y0, x1, y1;

    x0 = v[n-1].x - x;
    y0 = v[n-1].y - y;
    while( n-- ) {
        x1 = v->x - x;
        y1 = v->y - y;
        if( y0 > 0 ) {
            if( y1 <= 0 )
                if( x1*y0 > y1*x0 ) cross++;
        }
        else {
            if( y1 > 0 )
                if( x0*y1 > y0*x1 ) cross++;
        }
        x0 = x1; y0 = y1; v++;
    }
    return cross & 1;
}

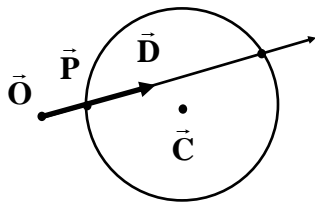
```



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## Ray-Sphere Intersection



**Ray:**  $\vec{P} = \vec{O} + t\vec{D}$

**Sphere:**  $(\vec{P} - \vec{C})^2 - R^2 = 0$

$$(\vec{O} + t\vec{D} - \vec{C})^2 - R^2 = 0$$

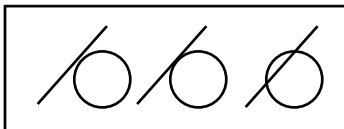
$$t = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$at^2 + bt + c = 0$$

$$a = \vec{D}^2$$

$$b = 2(\vec{O} - \vec{C}) \cdot \vec{D}$$

$$c = (\vec{O} - \vec{C})^2 - R^2$$



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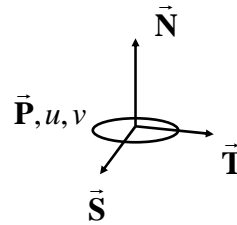
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# Geometric Methods

## Methods

- Find normal and tangents
- Find surface parameters



## e.g. Sphere

**Normal**  $\vec{N} = \vec{P} - \vec{C}$

**Parameters**

$x = \sin \theta \cos \phi$	$\phi = \tan^{-1}(x, y)$
$y = \sin \theta \sin \phi$	$\theta = \cos^{-1} z$
$z = \cos \theta$	

# Ray-Implicit Surface Intersection

$$f(x, y, z) = 0$$

$$x = x_0 + x_1 t$$

$$y = y_0 + y_1 t$$

$$z = z_0 + z_1 t$$

$$f^*(t) = 0$$

1. Substitute ray equation
2. Find *positive, real* roots

### Univariate root finding

- Newton's method
- *Regula-falsi*
- Interval methods
- Heuristics

# Ray-Algebraic Surface Intersection

$$p_n(x, y, z) = 0$$

$$x = x_0 + x_1 t$$

$$y = y_0 + y_1 t$$

$$z = z_0 + z_1 t$$

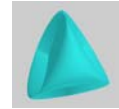
$$p_n^*(t) = 0$$

**Degree  $n$**

**Linear:** Plane

**Quadric:** Spheres, ...

**Quartic:** Tori



**Polynomial root finding**

- Quadratic, cubic, quartic
- Bezier/Bernoulli basis
- Descartes' rule of signs
- Sturm sequences

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## History

**Polygons**

**Quadrics, CSG**

**Tori**

**Bicubic patches**

**Superquadrics**

**Algebraic surfaces**

**Swept surfaces**

**Fractals**

**Height fields**

**Deformations**

**Subdivision surfs.**

**Appel '68**

**Goldstein & Nagel '71**

**Roth '82**

**Whitted '80, Kajiya '82**

**Edwards & Barr '83**

**Hanrahan '82**

**Kajiya '83, van Wijk '84**

**Kajiya '83**

**Coquillart & Gangnet '84, Musgrave '88**

**Barr '86**

**Kobbelt, Daubert, Siedel, '98**

**P. Hanrahan, A survey of ray-surface intersection algorithms**

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