

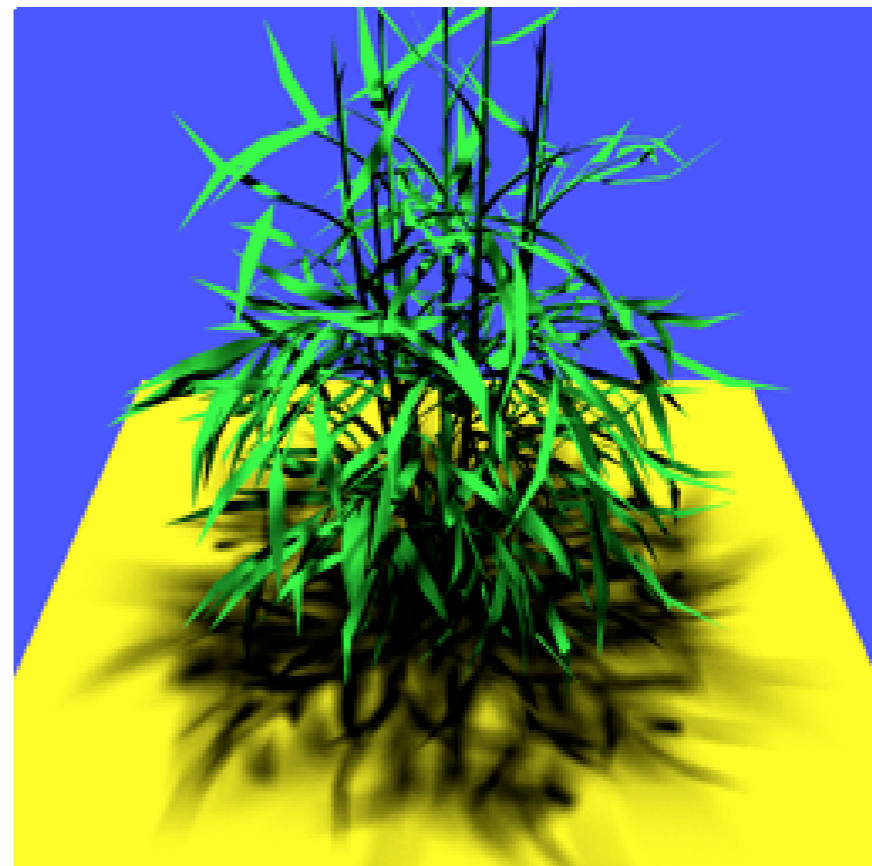
# Monte Carlo I: Foundations

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# Integration Challenges in Rendering

- Complex light geometry
- Complex visibility
- Discontinuous integrands
- Many times per pixel

$$E(x) = \int_{H^2} L_i(x, \omega) |\cos \theta| d\omega$$



# Advantages of MC Integration

- Few restrictions on the integrand
  - Doesn't need to be continuous, smooth, ...
  - Only need to be able to evaluate at a point
- Extends to high-dimensional problems
- Conceptually straightforward
- Efficient for solving at just a few points

# Disadvantages of MC

- Noisy
- Slow convergence
- Good implementation is hard
  - Debugging
  - Choosing appropriate techniques

# Overview

- Random variables
  - Sampling from distributions
- Basic MC estimator
- Variance
  - Definition and causes
  - Variance reduction: importance sampling
- Efficiency
  - Splitting & Russian Roulette

# Random Variables

- Definition

- $\bar{x}$  is chosen by some random process
- $\bar{x} \sim p(x)$  probability distribution function (pdf)
- pdf is non-negative, integrates to one
- *\*not\** necessarily  $\leq 1$ !

- Pdf examples

- $p(x) = 1, 0 \leq x < 1$
- $p(x) = 1/2, 5 \leq x < 7$
- $p(x) = \cos(x), 0 \leq x < \pi/2$
- $p(x) = \delta(x)$

# Probability Distributions

- Discrete

- Events  $\bar{x}_i$  with probability  $p_i \geq 0$   $\sum_{i=1}^N p_i = 1$

- Cumulative distribution  $P_j = \sum_{i=1}^j p_i$

- Can choose event with uniform random num.  $\xi$

- Continuous

$$\bar{x} \sim p(x) \qquad p(x) \geq 0$$

$$P(x) = \int_0^x p(x) dx$$

$$P(x) = \Pr(\bar{x} < x) \qquad \Pr(\alpha \leq \bar{x} \leq \beta) = P(\beta) - P(\alpha)$$

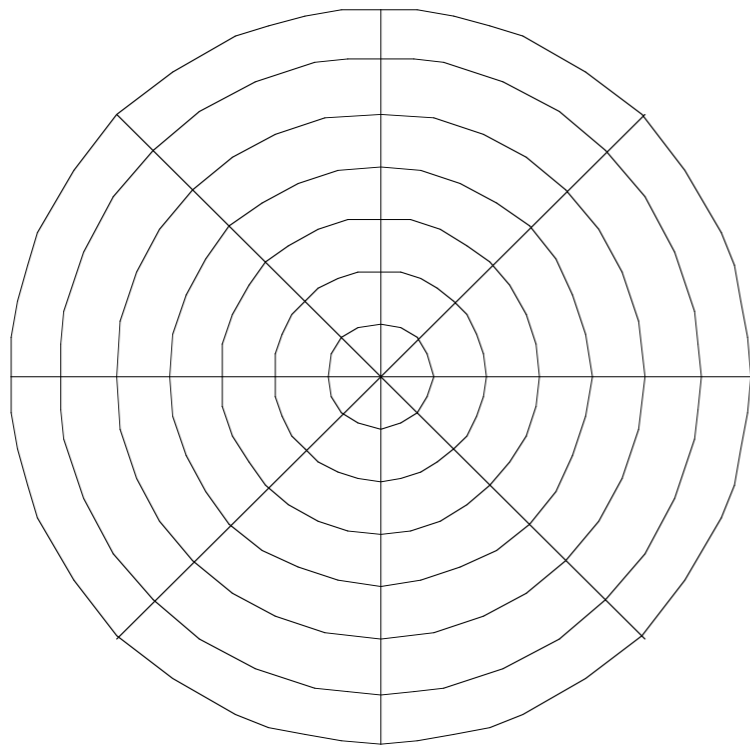
# Sampling the Power Function

- Given  $f(x) = x^n$
- Normalize to find pdf  $p(x)$
- Find cumulative distribution function  $P(x)$
- Solve to find  $\bar{x} = P^{-1}(\xi)$
  
- Trick:  $\bar{x} = \max_n(\xi_1, \dots, \xi_n)$



# Sampling a Circle

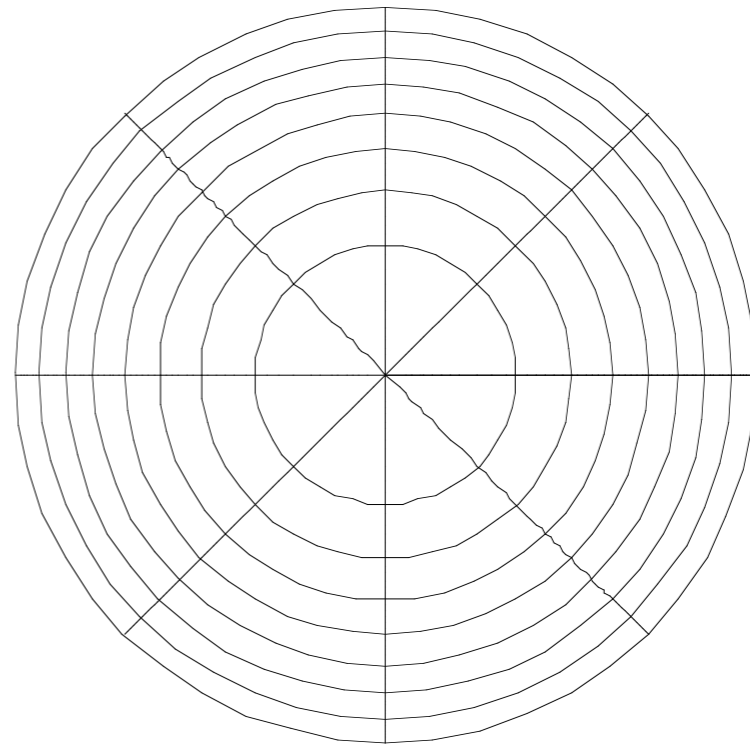
Wrong



$$\theta = 2\pi\xi_1$$

$$r = \xi_2$$

Right

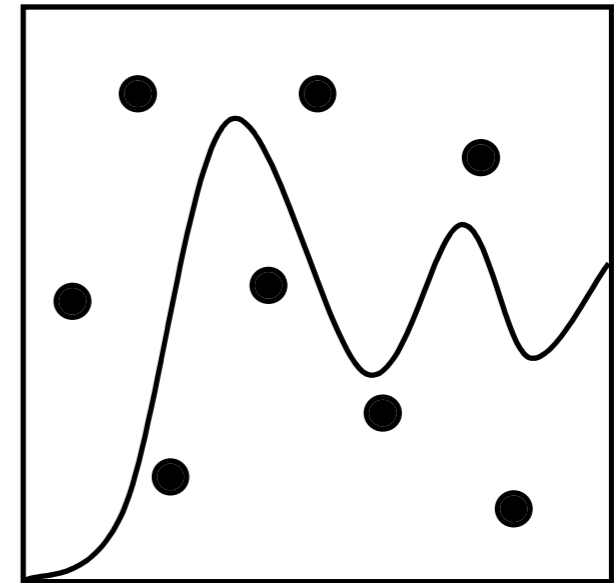


$$\theta = 2\pi\xi_1$$

$$r = \sqrt{\xi_2}$$

# Basic Rejection Sampling

- Pick  $\xi_1$  and  $\xi_2$
- Accept  $\xi_1$  if  $\xi_2 < c \cdot f(\xi_1)$
- Applications
  - Sampling points in a circle
  - Sampling directions on the sphere



# Expected Value

- Definition

$$E[f] \equiv \int_0^1 f(x)p(x)dx$$

- Key property: linearity

- Unbiased MC Estimator:

$$E \left[ \frac{1}{N} \sum_{i=1}^N f(x_i) \right] = \int_0^1 f(x)dx$$

# Unbiased MC Estimator

$$\begin{aligned} E \left[ \frac{1}{N} \sum_{i=1}^N f(x_i) \right] &= \frac{1}{N} \sum_{i=1}^N E[f(x_i)] && x_i \sim p(x) \\ &= \frac{1}{N} \sum_{i=1}^N \int_0^1 f(x) p(x) dx \\ &= \frac{1}{N} \sum_{i=1}^N \int_0^1 f(x) dx && \text{if } p(x) \text{ is uniform} \\ &= \int_0^1 f(x) dx \end{aligned}$$

Natural extension to multiple dimensions...

# Direct Lighting: Area Sampling

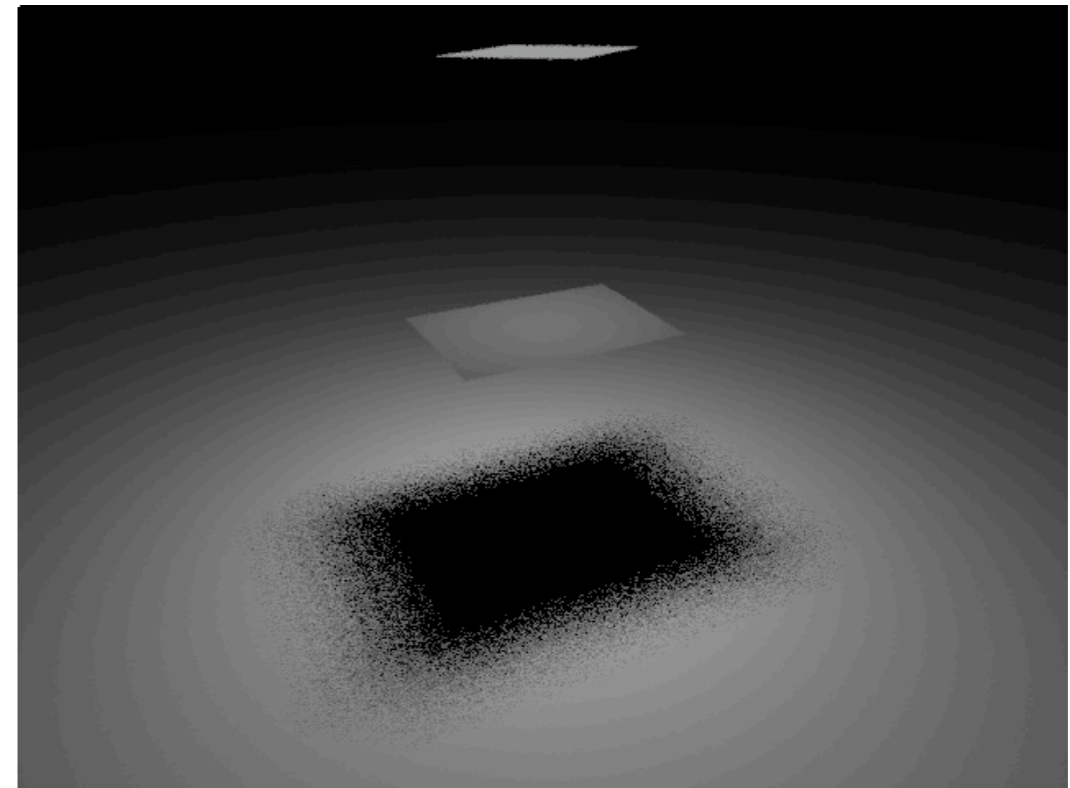
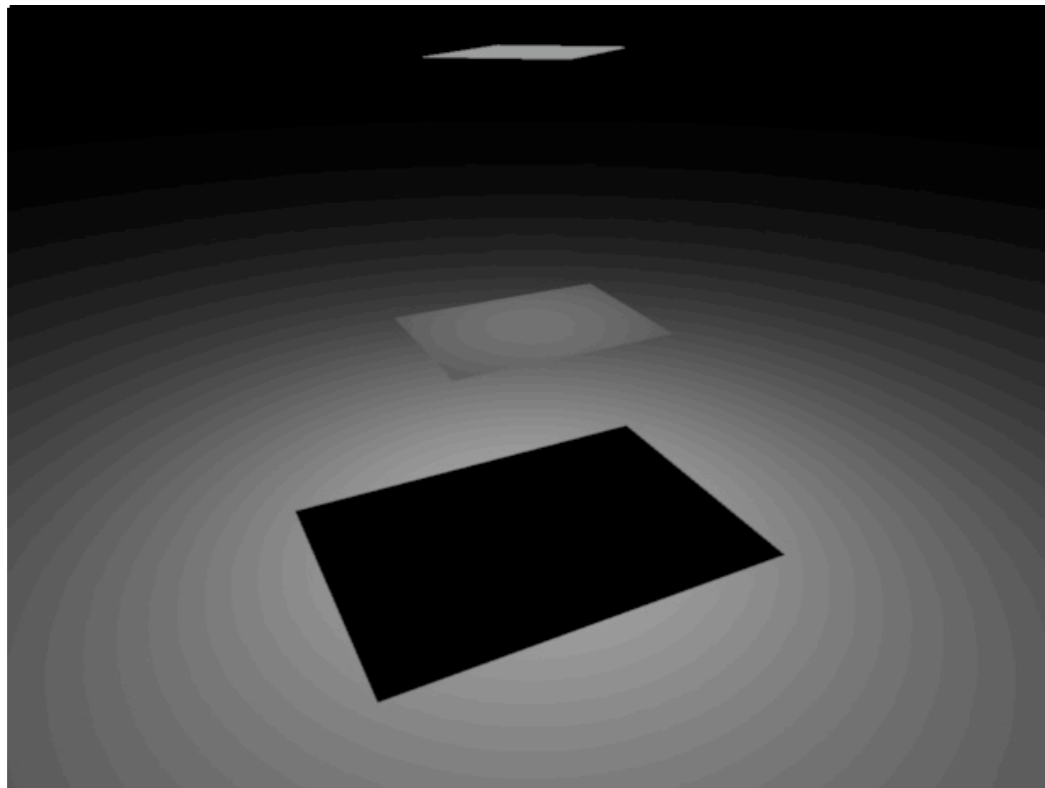
$$\begin{aligned} E(x) &= \int_{\Omega} L(x, \omega) \cos \theta d\omega \\ &= \int_A L(x_o, \omega_o) \frac{\cos \theta \cos \theta_o}{|x - x_o|^2} V(x, x_o) dA(x_o) \end{aligned}$$

Sample light uniformly by area

$$E(x) \approx \frac{1}{N} \sum_{i=1}^N L(x_{o[i]}, \omega_{o[i]}) \frac{\cos \theta \cos \theta_{o[i]}}{|x - x_{o[i]}|^2} V(x, x_{o[i]})$$

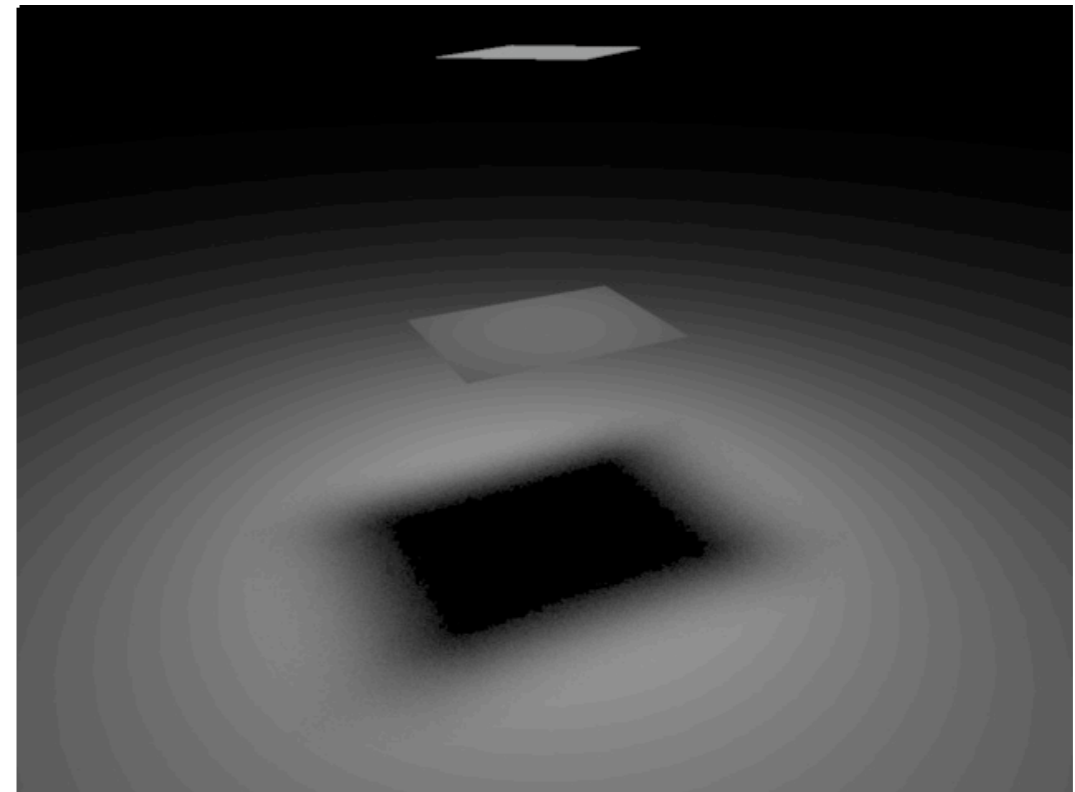
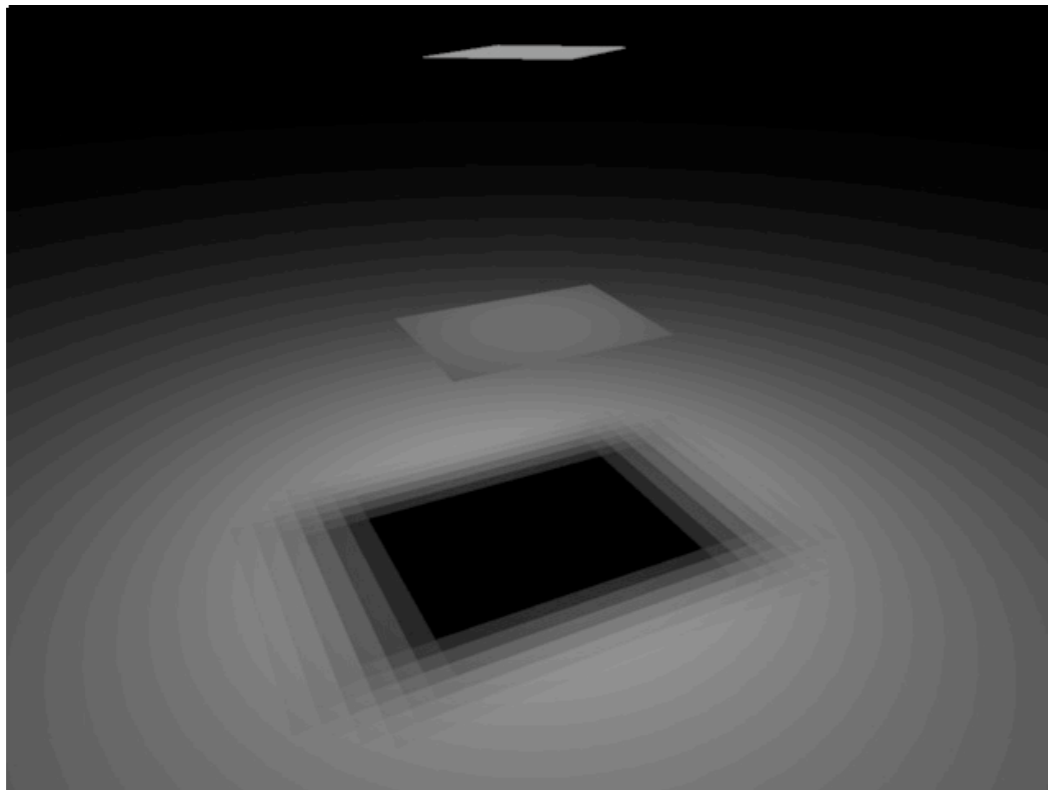
# Direct Lighting

4 eye rays, 1 shadow ray



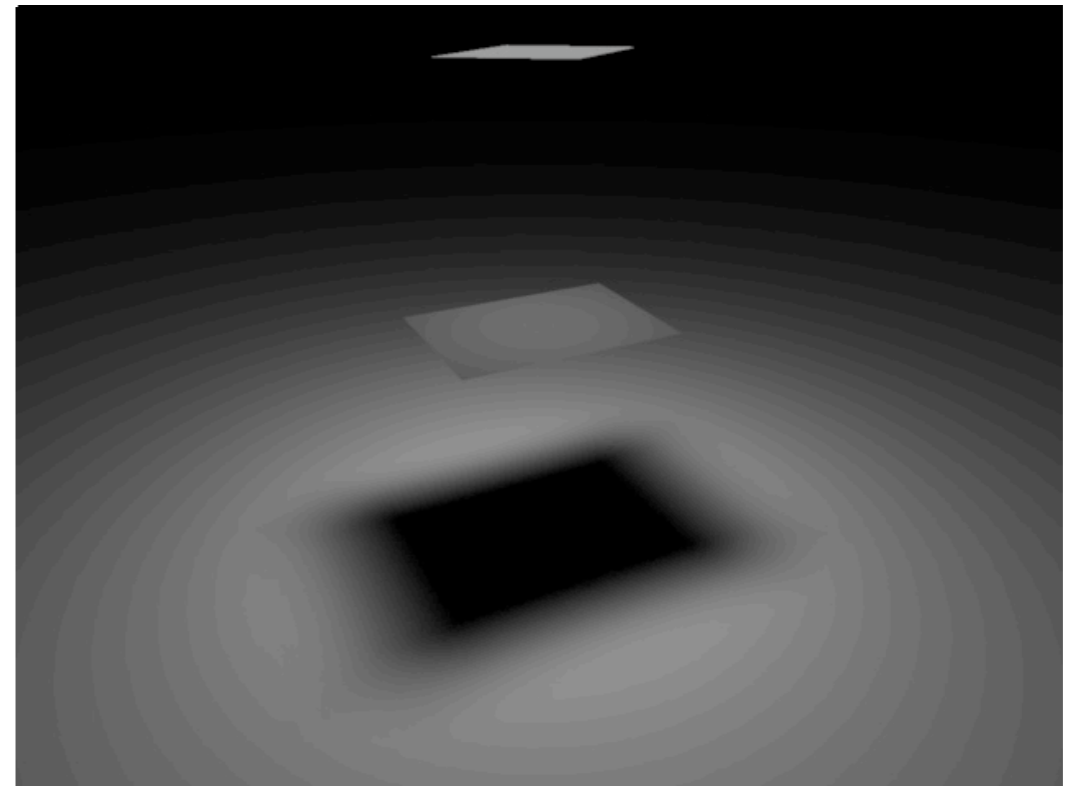
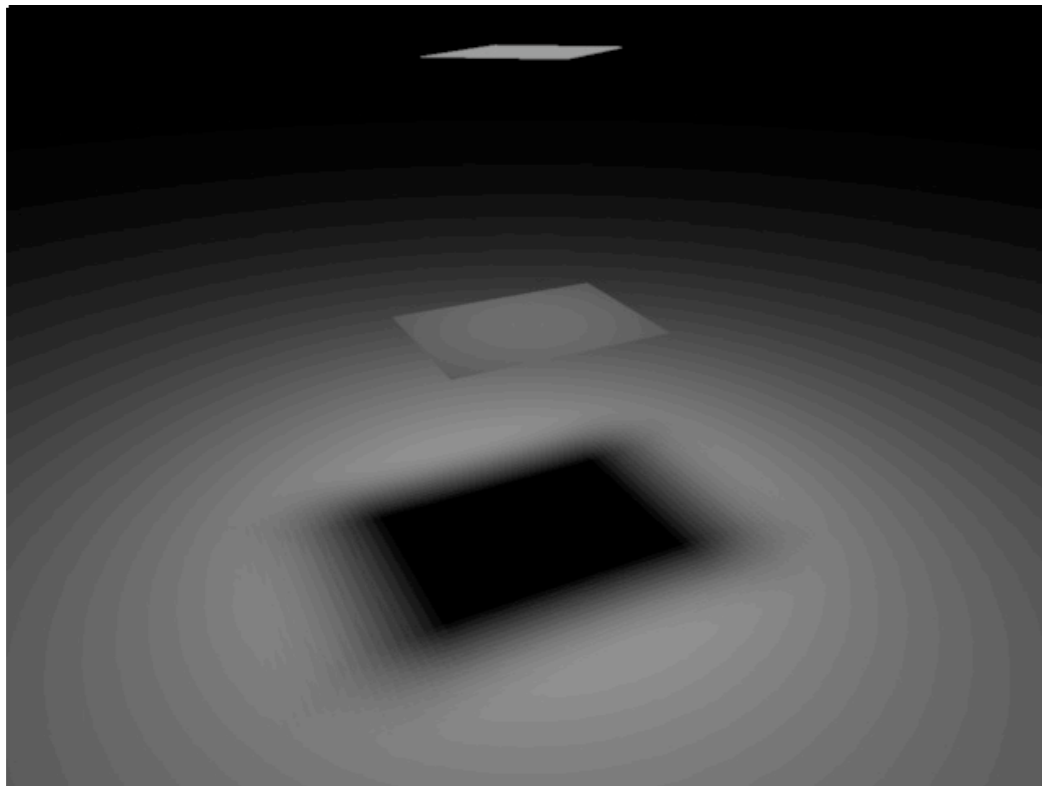
# Direct Lighting

4 eye rays, 16 shadow rays



# Direct Lighting

4 eye rays, 64 shadow rays





# Variance

- Definition

$$V[Y] \equiv E[(Y - E[Y])^2] = E[Y^2] - E[Y]^2$$

- Properties

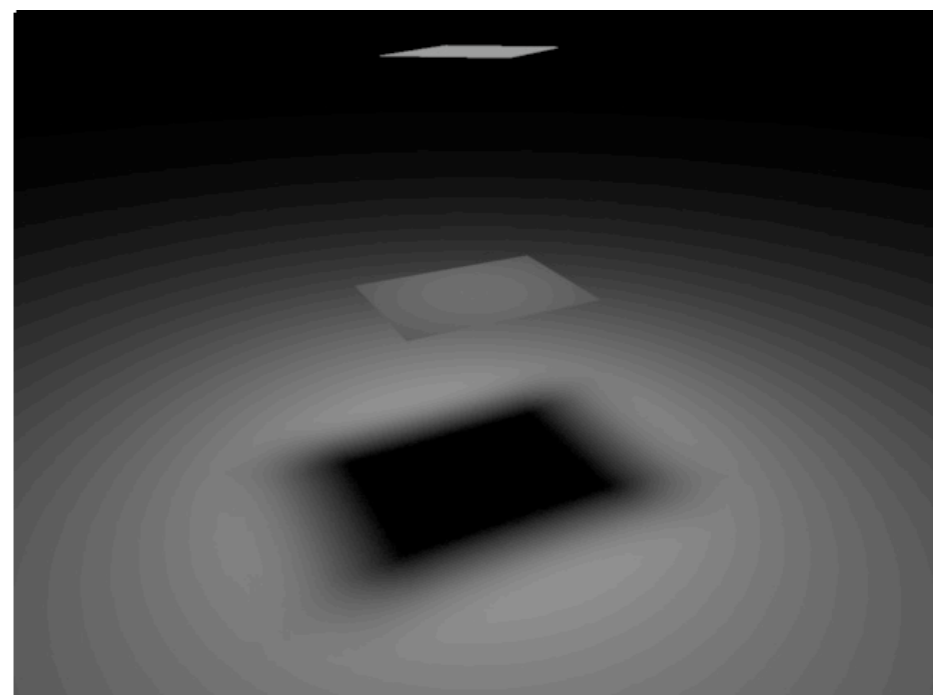
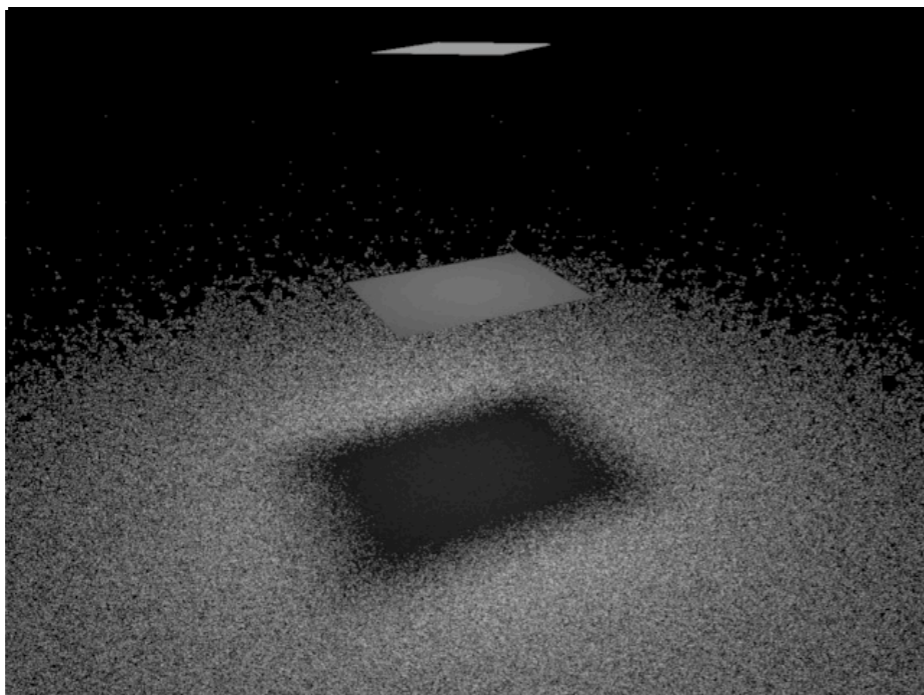
$$V[\sum Y_i] = \sum V[Y_i] \quad V[aY] = a^2 \sum V[Y]$$

- Variance decreases with sample size

$$V\left[\frac{1}{N} \sum Y_i\right] = \frac{1}{N^2} \sum V[Y_i] = \frac{1}{N} V[Y]$$

# Direct Lighting

- Directional sampling wastes samples where the integrand is zero



Basic MC strategy: focus samples where integrand is high (easier said than done)

# Improving Efficiency: Splitting

- Name from neutron transport applications
- Take additional samples in some dimensions

$$\int_0^1 \int_0^1 f(x)g(y)dx dy \approx \frac{1}{N} \sum f(x_i)g(y_i)$$
$$\approx \frac{1}{N_f} \sum_{i=1}^{N_f} f(x_i) \left( \frac{1}{N_g} \sum_{j=1}^{N_g} g(y_j) \right)$$

- e.g. multiple shadow rays

# Improving Efficiency: Russian Roulette

- Randomly skip computations with low expected value...in an unbiased manner
- Algorithm:
  - Determine probability of skipping  $p_s$
  - Choose uniform random number  $\xi$
  - Skip if  $\xi < p_s$
  - Otherwise estimate is  $\frac{f(x_i)}{1 - p_s}$

- Expected value

$$p_s \cdot 0 + (1 - p_s) \cdot E[f / (1 - p_s)] = E[f]$$

# Importance Sampling

- Try to sample where integrand is large

$$\begin{aligned} E \left[ \frac{1}{N} \sum_{i=1}^N \frac{f(x_i)}{p(x_i)} \right] &= \frac{1}{N} \sum_{i=1}^N E \left[ \frac{f(x_i)}{p(x_i)} \right] && x_i \sim p(x) \\ &= \frac{1}{N} \sum_{i=1}^N \int_0^1 \frac{f(x)}{p(x)} p(x) dx \\ &= \frac{1}{N} \sum_{i=1}^N \int_0^1 f(x) dx \\ &= \int_0^1 f(x) dx \end{aligned}$$